

# M-900iB/400L



Max. load capacity  
at wrist: 400 kg



Max. reach:  
3704 mm

# FANUC

| Robot  |         |      | Max load capacity at wrist (kg) | Reach (mm) | Controlled axes | Repeatability (mm) | Mechanical weight (kg) | Motion range [°] |     |     |     |     |     | Maximum speed [°/s] |    |    |     |     |     | J4 Moment/ Inertia | J5 Moment/ Inertia | J6 Moment/ Inertia | Average Power consumption (kW) | Protection             |                                  |
|--------|---------|------|---------------------------------|------------|-----------------|--------------------|------------------------|------------------|-----|-----|-----|-----|-----|---------------------|----|----|-----|-----|-----|--------------------|--------------------|--------------------|--------------------------------|------------------------|----------------------------------|
| Series | Version | Type |                                 |            |                 |                    |                        | J1               | J2  | J3  | J4  | J5  | J6  | J1                  | J2 | J3 | J4  | J5  | J6  |                    |                    |                    |                                | Body standard/optional | Wrist & J3 arm standard/optional |
| M-900  | iB      | 400L | 400                             | 3704       | 6               | ±0.1**             | 3150                   | 360              | 154 | 160 | 720 | 244 | 720 | 80                  | 80 | 80 | 100 | 100 | 160 | 2744/ 1098         | 2744/ 1098         | 1725/ 444          | 5                              | IP54/ IP56             | IP67                             |

● standard ○ on request - not available ( ) with hardware and/or software option \*\* Based on ISO9283

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Long arm



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